

SERVICE PHYSICS

Software support note: Establishing connection between host computer and the 6K4 motion control system.

As suggested by the number of components this system can become confusing and requires a mastery of some simple basic relationships between the components. The following block diagram shows the flow of information between the parts of the system.

The steps to set up communication are:

1. Set the Ethernet Adaptor IP 3 (IPv4) to 10.0.0.100
2. Set the Mask to 155.155.155.0
3. Find the SixKWiz wizard in the ESCA hawk 7 folder or in the Windows start
4. window. The Icon is a stick with a Gold Star at the top.
5. Open the wizard.
6. Unplug the Ethernet cable from the 6K4 controller to at the back of the computer.
7. Select next until you reach the window that allows you to select the RS232 Com
8. port. Start with port 1. Select next.
9. If the Wizard find the 6K4 you will get two sets of Ethernet parameters. The
10. values stored in the registry and the ones from the 6K4. They should match. If
11. they don't allow the Wizard to create a match.
12. 6. If you get an error close the wizard and start over. This time select the Com Port
13. Select next. This should work. If you still get a message that the connection
14. failed, check the RS232 cable connections at both ends. Check that the 6K4
15. power is on. Turn on if not. If it is on turn the 6K4 power off for 30 seconds and
16. then back on. The power switch is near the bottom of the panel. It is a black
17. rocker switch with a light.
18. 7. Retry both Com ports. When you get a valid Com Port result, Plug in the
19. Ethernet cable and proceed NEXT. If you get no message in the error description
20. box click on the Ping button above the error description box. If you get a PING
21. received message proceed NEXT. Then close the SixKWiz wizard.
22. Find the icon with snoopy. This is the Joystick setup icon. When you click it you should
- see a timer count to 1, 2 or 3 and then go away and you will find the snoopy icon in the
- hidden icon tray at the bottom right of the screen. He can have a green, yellow or red face.

- a. Green – Snoopy has control of the XYZR stage.
 - b. Yellow – Snoopy is waiting for a programmed motion to complete
 - c. Red – Snoopy has been disabled
23. If you right click the mouse, snoopy you will get a menu setting for snoopy.
 24. Open the ESCA hawk EU program you will find the menu item Motion Control Panel at the bottom of the View Menu list. This will give you a read out of your position and controls to move the stage. If should have a manual on using this control and also how to program a list of positions and associate recipes with each position.
 25. You now have the Ethernet connection established

This block diagram shows the interconnections and will be useful in trouble shooting problems.

